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C. Control and Signal Modules

VH10—Discrete Signal Module

1. Product Overview

The discrete control/signal modules are required to provide a means for the customer to communicate with and control the Tool Changer.

M12, 4-socket, D-coded connectors are provided for passing through Ethernet signals between VH10 master and tool modules to support Tool Changer and customer-specified I/O.

On the master module (6) separate M12 male, 5-Pin connectors are provided to support and interface with a supplied PROFINET I/O block. These connections support Tool Changer Lock, Unlock and RTL (Ready-To-Lock) Tool-ID and power proximity sensor inputs as well as Tool Changer valve Latch and Unlatch output and Tool-ID.

An interface is also provided on the master module for support of an integrated solenoid valve (DC Voltage). The integrated valve can be supplied as part of the valve adapter block, 9121-Jxx-M. Refer to the valve adapter block manual for more information (9620-20-C-Air and Valve Adapters).

When the Tool Changer is coupled, the master and tool modules communicate across their interface using a spring loaded pin block. A flexible boot surrounds the pin block to seal the connection from moisture and liquid while coupled.

The VH10 modules are designed with special features to afford the user the opportunity to operate the Tool Changer in the safest manner possible. In addition to providing the standard Locked, Unlocked, and Ready-to-Lock sensor inputs the VH10 modules are outfitted with patented Tool Stand Interlock (TSI) technology. The TSI feature consists primarily of a physical break in the unlock solenoid valve circuit. The TSI circuit is made available to the customer via an M12 female, 4-socket connector on the tool module. Using this connector, a mechanical switch, and trip dog can be integrated by the customer to allow the unlock solenoid valve circuit to be completed only when the tool is in the Tool Stand (see Figs. 1.1 and 1.2). A momentary action single-pole, double-throw switch is suggested.

In order to allow the Tool Changer to uncouple when a tool is not present, a relay circuit in parallel with the TSI circuit is utilized. This relay circuit is located in the master module and is triggered by the RTL sensor. If the RTL sensor is low, indicating no tool presence, then the relay circuit is closed, thus allowing the unlock solenoid valve circuit to be completed. If the RTL sensor is high, indicating tool presence, then the relay circuit is open and the TSI circuit on the tool-side must be closed in order to complete the unlock solenoid valve circuit.

Monitoring of the relay circuit is achieved through the RTL input. Refer to Table 3.1 for suggested fault monitoring conditions.

Refer to Section 7 for module specifications and Section 8 for drawings and specific connector details.

Figure 1.1—VH10 Modules

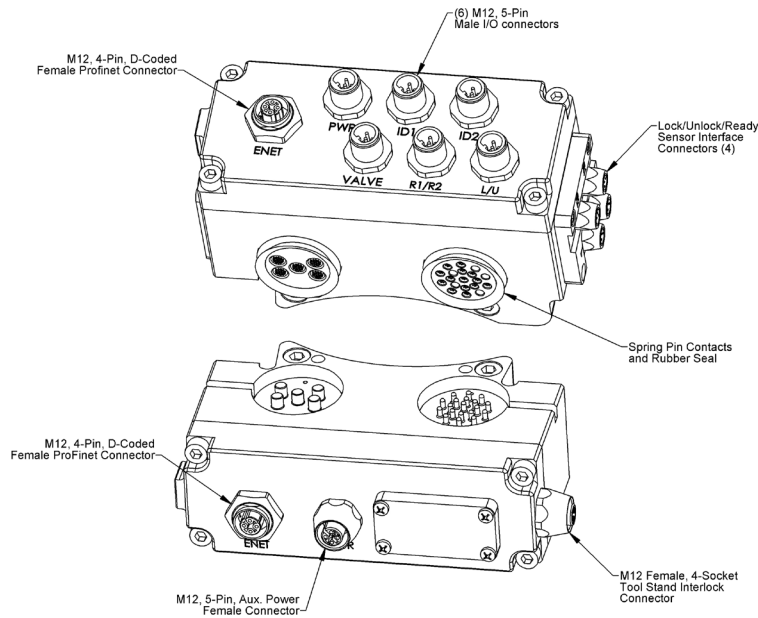
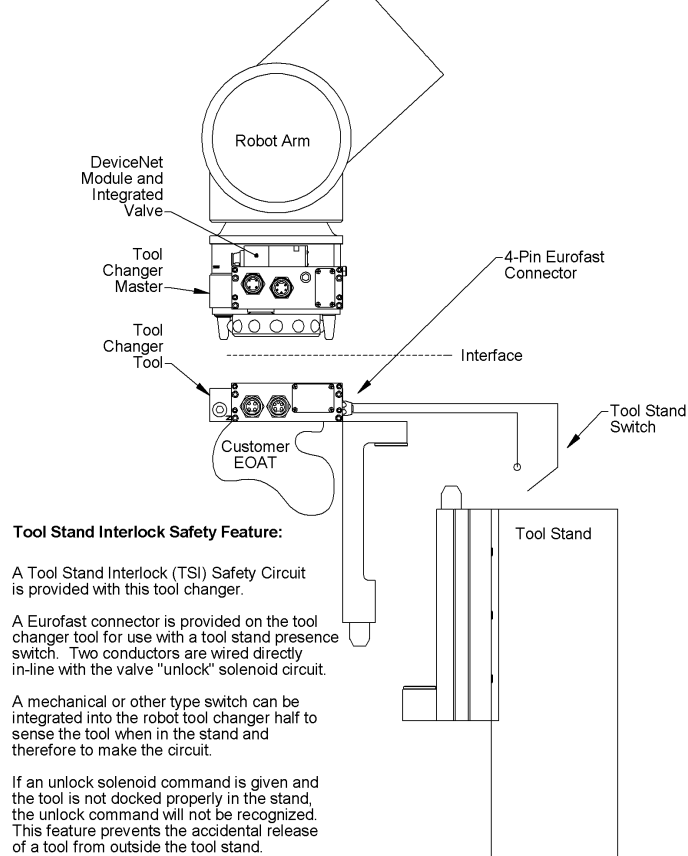


Figure 1. 2—Tool Stand Interlock (TSI)



CAUTION: The Tool Changer is equipped with Tool Stand Interlock (TSI). Special procedures are required to unlock the Tool Changer.

2. Installation

The control/signal modules are typically installed by ATI prior to shipment. The steps below outline the field installation or removal as required.

For wiring information refer to the drawings in Section 8.



WARNING: Do not perform maintenance or repair on Tool Changer or modules unless the tool is safely supported or docked in the tool stand and all energized circuits (e.g. electrical, air, water, etc.) have been turned off. Injury or equipment damage can occur with tool not docked and energized circuits on. Dock the tool safely in the tool stand and turn off all energized circuits before performing maintenance or repair on Tool Changer or

2.1 Installing

1. It may be necessary to clean the mounting surface on the Tool Changer prior to installing the module in order to remove any debris that may be present.
2. Using the ledge feature as a guide place the module into the appropriate location on the Tool Changer body. Align the module with the Tool Changer using the dowels in the bottom of the ledge feature. Apply Loctite 242 to the supplied M6 SHCS fasteners and tighten to 110 in-lbs.
3. Typically, proximity sensor and valve cables need to be connected to the Master side control module. These connections can be made after attaching the module to the Tool Changer body. Customer connections up to the module can also be made after the module is installed. Ensure that the connectors are cleaned prior to being secured as appropriate.

2.2 Removal

1. Prior to removing the module use a marker pen to scribe a line or indication between the Tool Changer and module body as a reminder where the module is to be re-installed.
2. Depending upon the service or repair being done, customer connections up to the module may or may not need to be disconnected. Also, proximity sensor and valve cables may or may not need to be disconnected.
3. Remove the socket head cap screws and lift the module from the Tool Changer.

3. Operation

M12, 4-socket connectors are provided on the control/signal master and tool modules for customer interface to downstream I/O. The M12 connector wiring is compatible with that of an off-the-shelf PROFINET I/O block that is integrated into the overall Tool Changer package.

Integrated connections Locked, Unlocked and Ready-to-Lock proximity sensor input connections are provided for confirmation of Tool Changer and locking mechanism positions.

(3) Separate M12, 5-Pin connectors on the master module support an interface to Tool Changer Locked, Unlocked and RTL proximity sensor inputs as well as Latch and Unlatch valve outputs. Cables are provided in the overall Tool Changer package to connect these signals to the supplied PROFINET I/O block. This interface allows for confirmation and control of the Tool Changer and locking mechanism position. Please refer to drawings in Section 8 for details.

Refer to the specific Tool Changer manual for details on the operation of the Tool Changer and recommended procedure for coupling.

When the Tool Changer is coupled, the discrete module tool can be communicated with, downstream I/O can be read and attached end-effectors can be used.

3.1 Operation Flow Chart

Refer to the flow chart in Figure 3.1 for a logical description of Tool Changer operation, lock/unlock procedures and diagnostic checks.

4. Maintenance

Once installed the operation of the control modules is generally trouble free. The modules are not designed to be field serviced as all point-to-point wiring connections are soldered. Component replacement is limited to the V-Ring seal on the Master.



WARNING: Do not perform maintenance or repair on Tool Changer or modules unless the tool is safely supported or docked in the tool stand and all energized circuits (e.g. electrical, air, water, etc.) have been turned off. Injury or equipment damage can occur with tool not docked and energized circuits on. Dock the tool safely in the tool stand and turn off all energized circuits before performing maintenance or repair on Tool Changer or modules.

If the Tool Changer is being used in dirty environments (e.g., welding or deburring applications), care should be taken to limit the exposure of the Tool Changer. Idle Tool assemblies should be covered to prevent debris from settling on the mating surface. Also, the Master assembly should be exposed for only a short period of time during Tool change and down time.

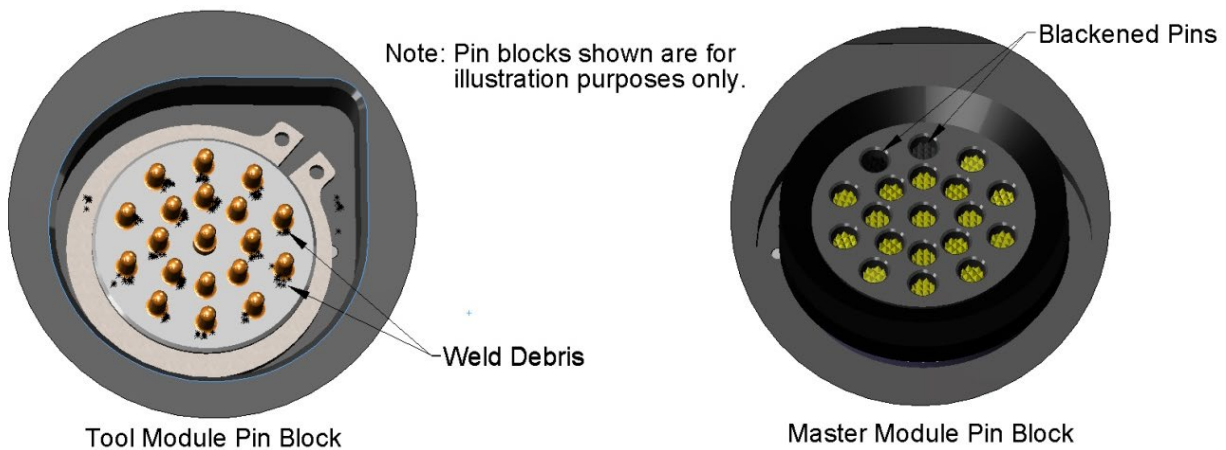
Under normal conditions, no special maintenance is necessary, however it is recommended that periodic inspections be performed to assure long-lasting performance and to assure that unexpected damage has not occurred. Perform the following visual inspection monthly:

- Inspect mounting fasteners to verify they are tight and if loose, then tighten to the proper torque.
- Cable connections should be inspected during maintenance periods to ensure they are secure. Loose connections should be cleaned and re-tightened as appropriate. Inspect cable sheathing for damage, repair or replace damaged cabling. Loose connections or damaged cabling are not expected and may indicate improper routing and/or strain relieving.
- Inspect the Master and Tool pin blocks for any pin damage, debris or darkened pins. Refer to [Section 4.1—Pin Block Inspection and cleaning](#).
- Inspect V-Ring seals for wear, abrasion, and cuts. If worn or damaged, replace. Refer to [Section 4.2—Seal Replacement](#).

4.1 Pin Block Inspection and cleaning

1. Inspect the Master and Tool pin blocks for any debris or darkened pins.

Figure 4.1—Inspect Master and Tool Pin Blocks

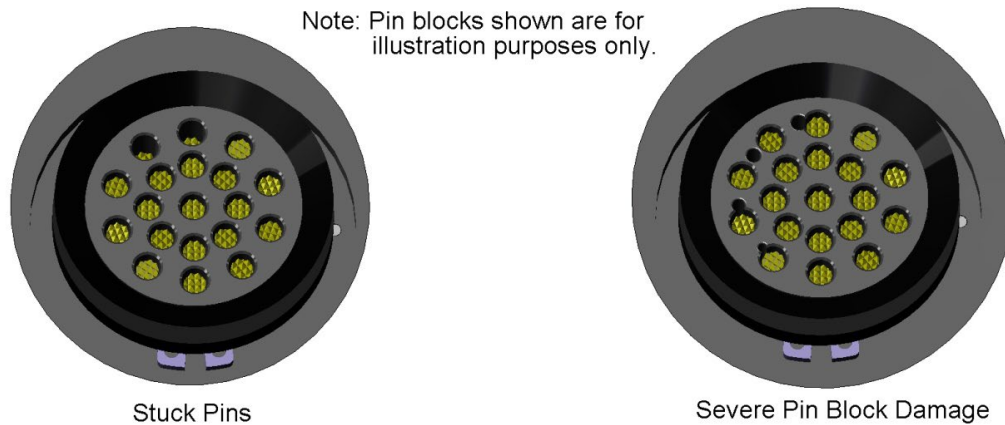


2. If debris or darkened pins exist, remove debris using a vacuum, and clean using a nylon brush (ATI part number 3690-0000064-60).

NOTICE: Do not use an abrasive media, cleaners, or solvents to clean the contact pins. Using abrasive media, cleaners, or solvents will cause erosion to the contact surface. Clean contact surfaces with a vacuum or non-abrasive media such as a nylon brush (ATI part number 3690-000064-60).

3. Inspect the Master and Tool pin blocks for stuck pins or severe pin block damage.

Figure 4.2—Stuck Pin and Pin Block Damage



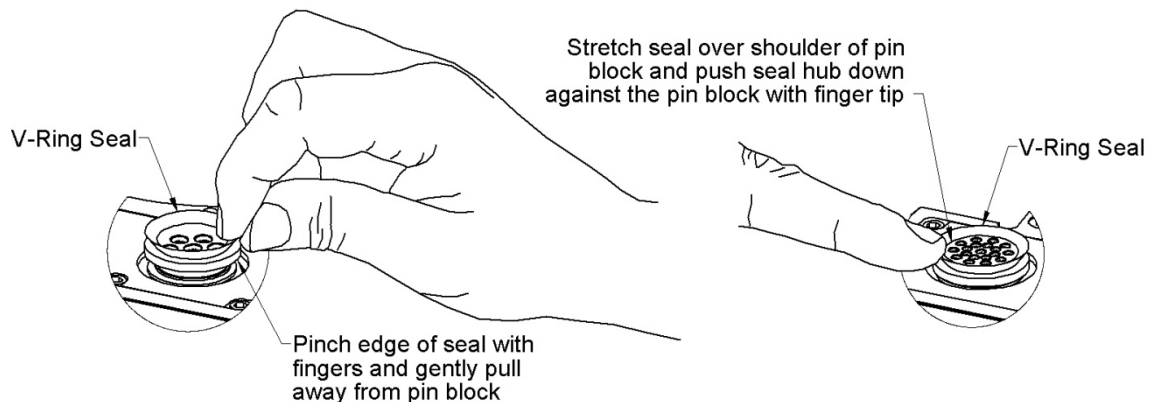
4. If stuck pins or severe pin block damage exists, contact ATI for possible pin replacement procedures or module replacement.

4.2 Seal Replacement

Replace the V-Ring seal:

1. To remove the existing seal, pinch edge of seal with fingers and gently pull the seal away from the pin block on the Master.
2. Pull the seal off the pin block.
3. To install a new seal, stretch the new seal over the shoulder of the pin block.
4. Push the seal's hub down against the pin block using finger tip.

Figure 4.3—V-Ring seal Replacement



5. Troubleshooting

Symptom	Possible Cause / Correction
Unit will not lock or unlock	Verify that ball bearings are moving freely. Clean and lubricate as needed. Check air supply. Check that exhaust port is properly vented (check muffler). Check valve for proper operation. Verify that discrete signals are mapped and are communicating properly. Verify that the Master and Tool are within the specified No-Touch zone when attempting to lock. Check TSI circuit for proper operation.
Sensors not operating properly	Verify that cables are connected correctly. Verify that the sensors are set correctly. Ensure that the Tool Plate is securely held to the Master Plate, that nothing is trapped between their surfaces, and that there is no air trapped in the Unlock (U) air port. Replace cables and/or sensors.
Loss of Communication	Check/Replace signal cabling up- and down-stream of Tool Changer modules. Inspect module contact pins for debris/wear/damage. Check product up- and downstream of Tool Changer for failure. This failure can "appear" to be caused by the Tool Changer or affect Tool Changer performance.

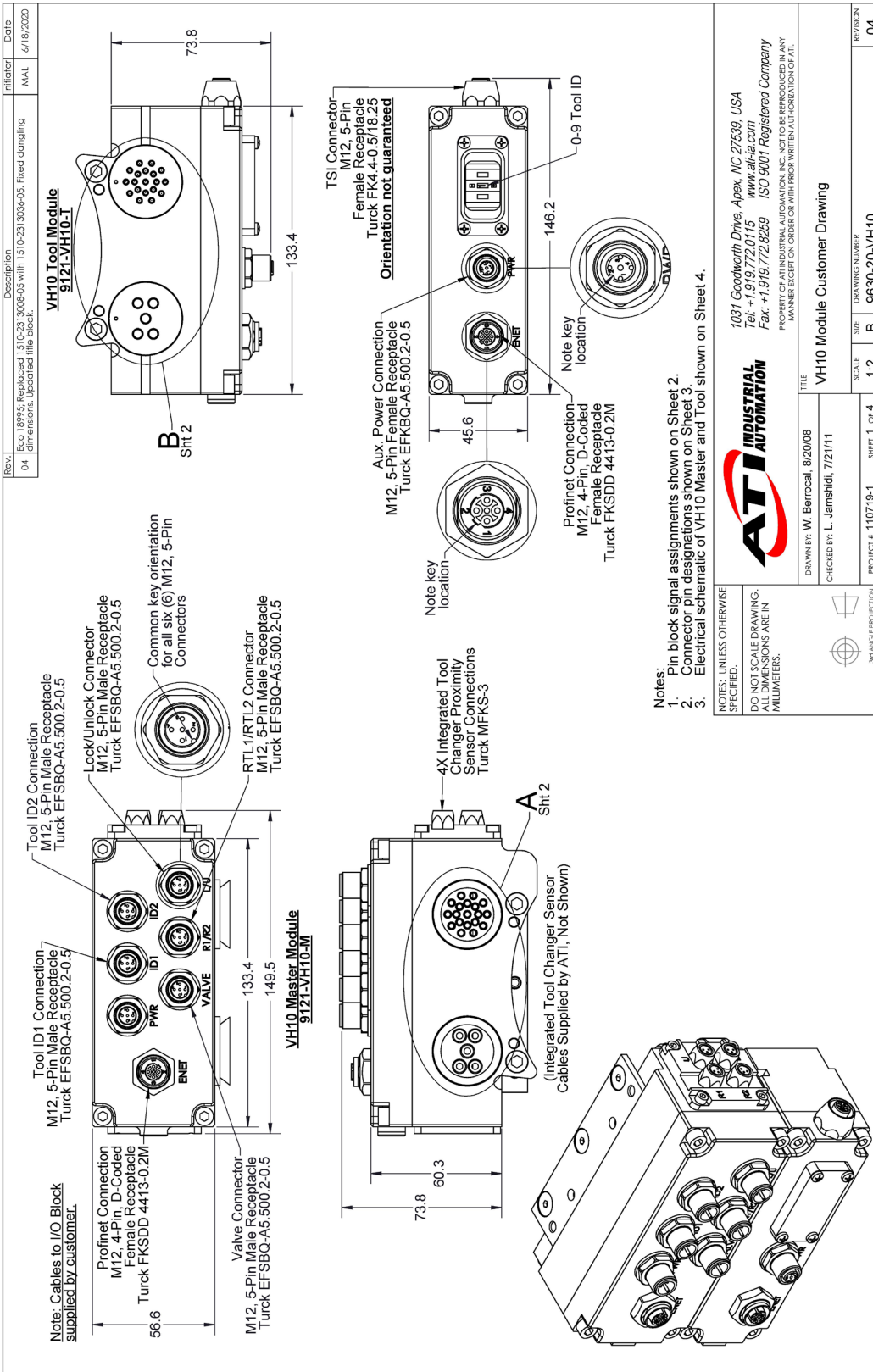
6. Recommended Spare Parts

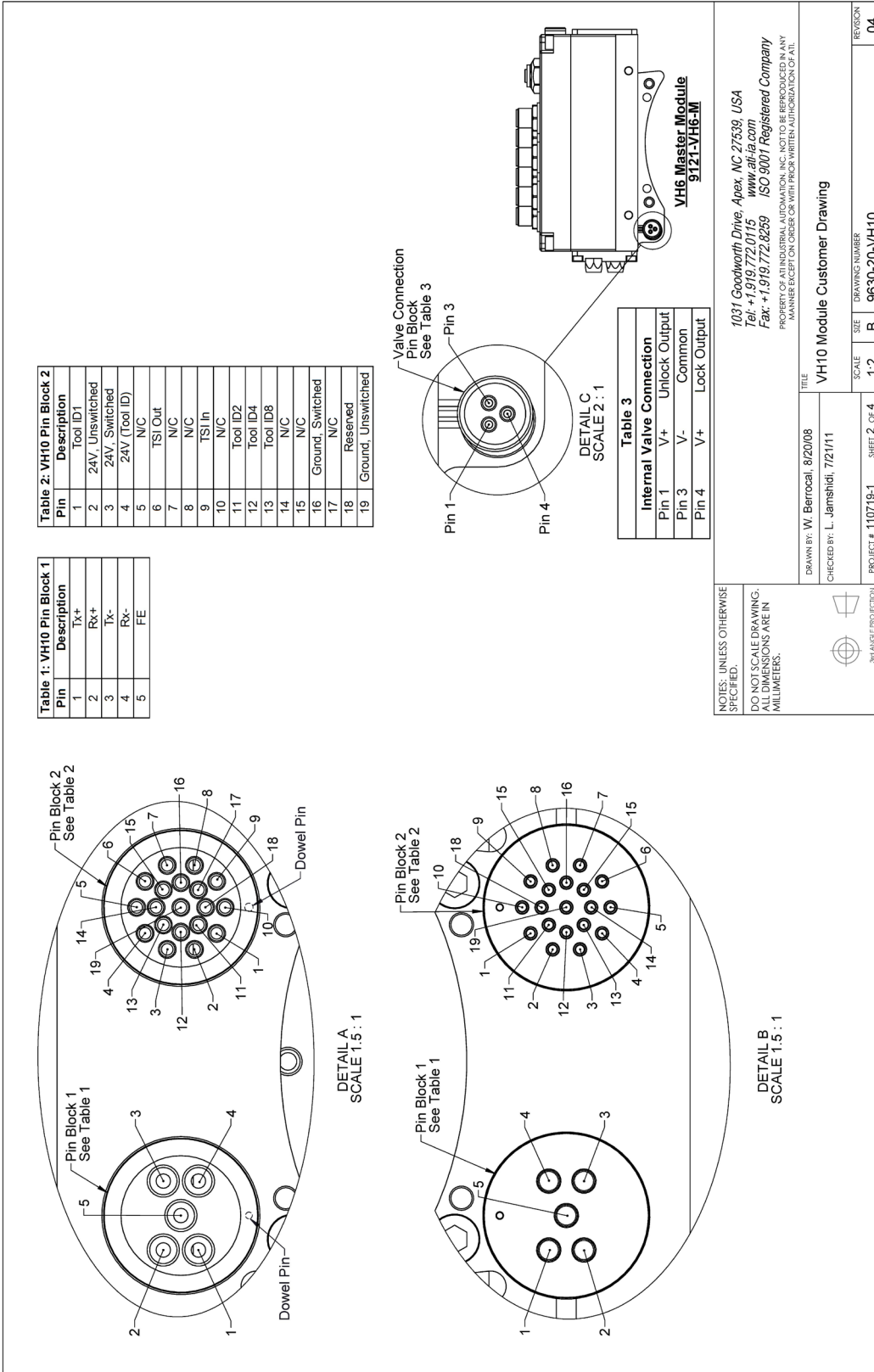
See Drawings in Section 8.

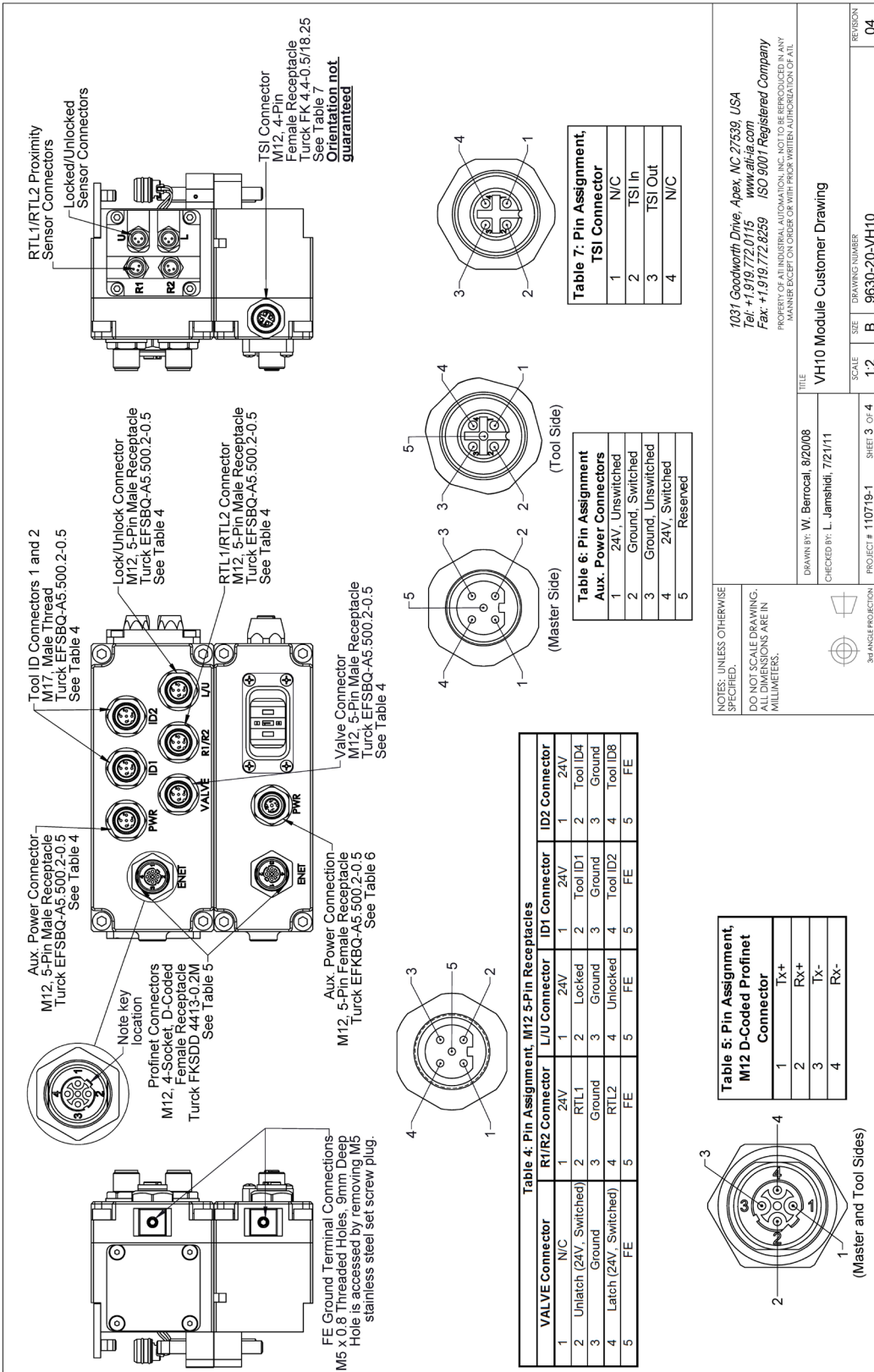
7. Specifications

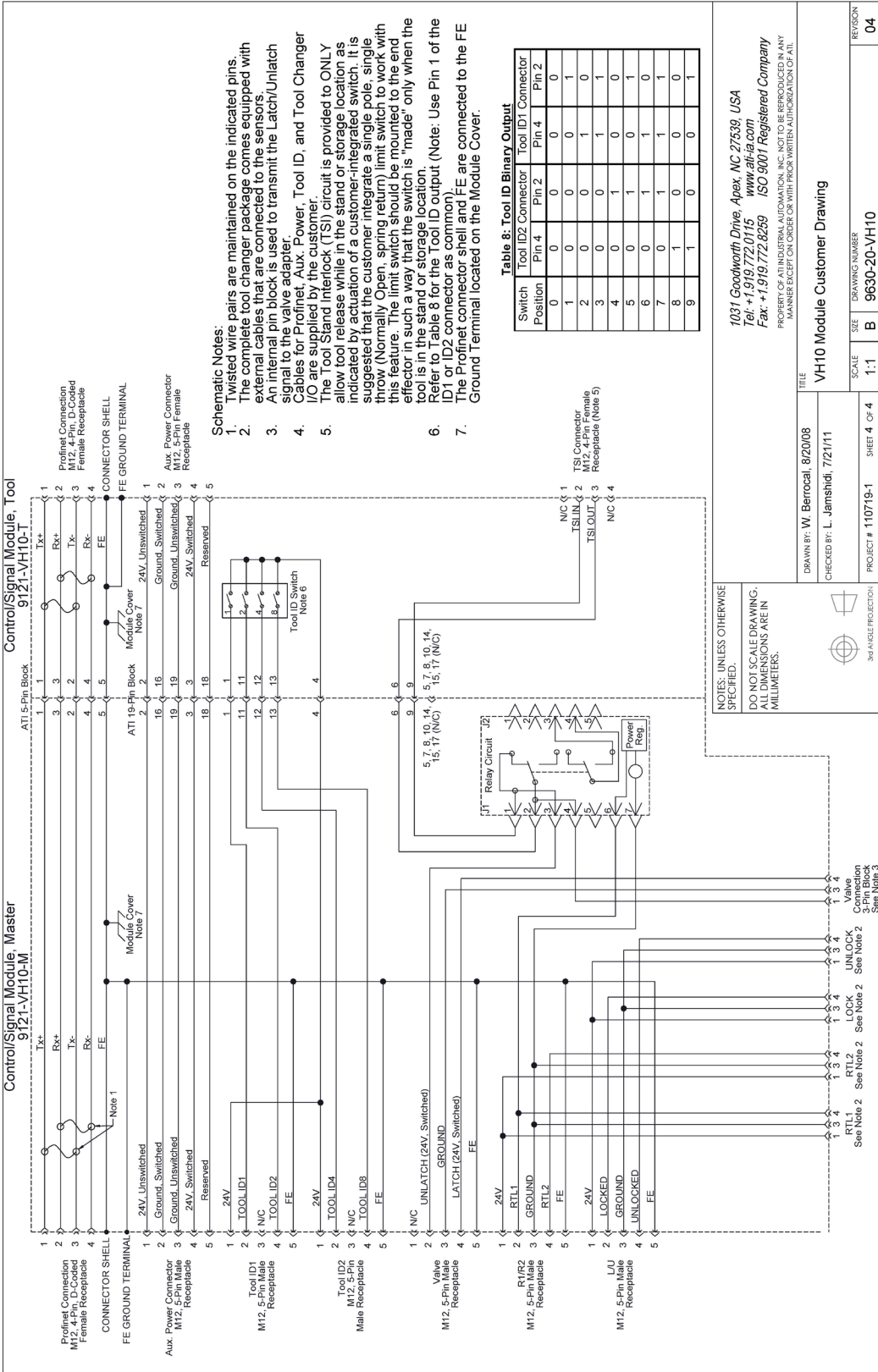
VH10-M		Discrete Module Supporting Integrated Solenoid Valve (DC Voltage), Tool Changer I/O and PROFINET I/O Block. Mates with VH10 Tool.
Connector(s)	FKSDD 4413 (3) @ FS 4.5–0.5/18.25	M12, 4-socket, female Tool Changer Connection compatible with PROFINET I/O Block. M12 Male, 5-Pin Discrete I/O Point Connection(s).
Weight	1.72 lbs (0.78 kg)	Master side
Pass-Through Signals	19 @ 5A, 250V	Fold-plated, spring-loaded and no-touch contact pins.
VH10-T		Discrete Module with 19-pin block Supporting PROFINET I/O Block and TSI on Tool. Mates with VH10-M.
Connector(s)	CKF 17–17 FK 4.4–0.5/18.25	M23 Female, 17-Socket Tool Changer Connection compatible with PROFINET I/O Block. M12 Female, 4-Socket TSI Connection.
Weight	1.42 lbs (0.64 kg)	Tool side
Pass-Through Signals	19 @ 5A, 250V	Gold-plated contacts w/ first mate ground pin.
Jxx-M		Valve Adapter
	250mA @ 24VDC	Integrated single solenoid valve, e.g. 9121-JC2-M. (MAC 48 Series, 48B-AUA-000-GEUA-1GB MOD4507) Valve power and control supplied through PROFINET I/O Block and M12, 5-Pin “Valve” Connector.
PROFINET I/O Block		See drawings in Section 8. Alternate I/O blocks available from Turck (FLDP-IOM124-0001) and Siemens (Simatic-ET200R).

8. Drawings







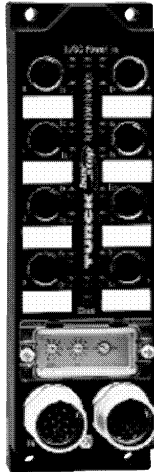
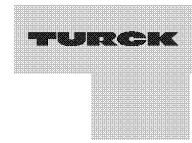


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VH10 Module Customer Drawing

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 PROJECT # 110719-1 SHEET 4 OF 4

SCALE: 1:1
 DRAWING NUMBER: 9630-20-VH10
 REVISION: 04



The FLDP-IOM124-0001 *busstop*[®] station provides a direct connection to PROFIBUS-DP. Up to twelve 2-/3-wire pnp sensors and up to four actuators with an output current of 2 A each may be connected to the station.

The inputs feature common short-circuit monitoring. The signal status of the inputs/outputs is indicated by green LEDs. The ON-LINE/OFF-LINE status of the station is signalled by a green/red LED.

The robust station is epoxy-encapsulated and equipped throughout with metal connectors.

Connection to PROFIBUS-DP is accomplished with 17-pole round connectors. The station supports transmission rates of up to 12 Mbps and adjusts automatically to the communication rate determined by the master station. The address of the station is set via two rotary switches located under a protective cover. It can be set from 0 to 99.

Power is also fed via a 17-pole connector. A green Power LED indicates that the station is powered, while a red Power LED indicates that the load voltage is missing. If the load voltage falls below the minimum value of 18 VDC, the Power LED turns red.

The robot module can be connected to the earth potential via the external earthing screw. The earth (PE) is capacitively coupled with the shield of the bus cable.

The GDS file can be downloaded from the internet under www.turck.com.

FLDP-IOM124-0001

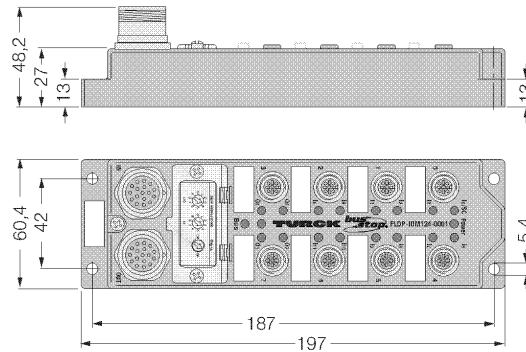
- Robust PROFIBUS-DP station
- 6 x 2 inputs and 2 x 2 outputs

Applications

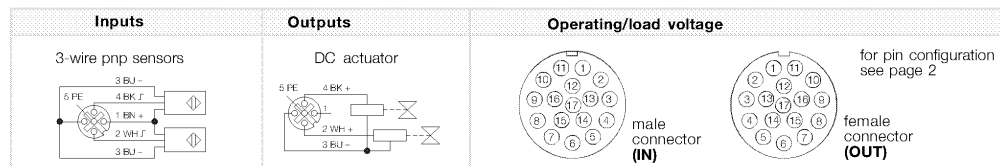
- For robot applications
- For connection of twelve 2/3 wire sensors or mechanical contacts
- For connection of four actuators, 2 A max. each

Special features

- Common short-circuit monitoring of pnp inputs
- Glass fibre reinforced plastic housings with encapsulated electronics and nickel-plated brass connectors meet protection degree IP67
- Transmission rate up to 12 Mbps
- Intelligent bus terminator

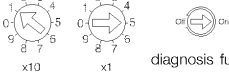


Wiring diagram





Input/output module FLDP-IOM124-0001
6 x 2 inputs/2 x 2 outputs, 24 VDC

Type Ident-no.	FLDP-IOM124-0001 6825347
Operating/load voltage Internal current consumption	18...30 VDC < 200 mA (from operating voltage)
Adjustments Address diagnosis function „U _L “ In this example address 15 is set	0...99 (decimal) via 2 rotary switches located under protective cover disabling of the diagnosis function via U _L 
Input circuits Input voltage Input current Switching threshold OFF / ON Input time delay Switching frequency Isolation	(12) pnp 3-wire sensors/2-wire sensors 18...30 VDC (from operating voltage) total input current ≤ 500 mA, short-circuit protection 2 mA / 4 mA 2.5 ms < 250 Hz to bus
Output circuits Output voltage Output current Switching frequency Isolation	(4) DC actuators 18...30 VDC (from load voltage) 2 A per output, short-circuit protection < 250 Hz to bus
LED indications Bus Voltage supply I/O status Common short-circuit indication (LED SC)	green/red: normal operation/no communication green/red: normal operat./load voltage missing (12) green: input ON / (4) green: output ON red: short-circuit at one input
Connection Operating and load voltage Bus line Inputs/outputs	17-pole round connector 17-pole round connector M12 x 1 connector
Bus terminator	automatic activation of the internal bus terminator if pin 15 and pin 16 of 17-pole female connector are not shorted

Pin configuration

17-pole round connector		
IN		OUT
1	1	0 V, U _B
2	2	0 V, U _L
3	3	+24 V, U _L
4	4	+24 V, U _B
5	5	PE
6	6	B-line
7	7	
8	8	
9	9	
10	10	
11	11	A-line
12	12	
13	13	
14	14	
15	15	reserved
16	16	reserved
17	17	

I/O data mapping
 Abbreviations:
 C0P4 = connector 0, pin 4,
 C1P2 = connector 1, pin 2
 0 = off, 1 = on
 SC = common short-circuit indication of inputs, I > 500 mA
 U_L = load voltage, U_L < 18 VDC
 U_B = operating voltage U_B < 18 VD

		Bit	7	6	5	4	3	2	1	0
Input	Byte 0	C4P2	C4P4	C2P2	C2P4	C1P2	C1P4	C0P2	C0P4	
Input	Byte 1	-	-	-	-	C6P2	C6P4	C5P2	C5P4	
Output	Byte 0	-	-	-	-	C7P2	C7P4	C3P2	C3P4	
Diagnose	Byte 0	-	-	-	-	-	-	U _B	U _L	SC

Housing Material Mounting Protection degree (IEC 60529/EN 60529) Shock and vibration test Temperature range	197 x 60 x 27 mm (h x w x d) PA6-GF30; nickel-plated brass connectors via 4 through-holes, Ø 5.3 mm IP67 (NEMA 1, 3, 4, 12, 13) according to EN 60068-2-6/2-27 0 °C up to +55 °C (32 °F up to +131 °F)
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