| Rev. | Description | Initiator | Date |
| :--- | :--- | :--- | :--- |
| 01 | Initial Drawing | ERDO | $1 / 7 / 2014$ |
| 02 | ECO 12273: Changed arrow formatting, updated $9005-20-2286$. | DBoh | $6 / 20 / 2014$ |

## Step 1

Place the Tool in the Tool
Stand. Programs should be written with the Tool Plate resting in the Tool Stand


Step 2:
Mount the Tool Side aid over the Too Plate by inserting the Locating Pins into the Bushings.

Step 3:


Mount the Master Side Aid to the QC Master Plate ensuring that the taper pins enter the corresponding holes in the Master Side Aid.
Energize the Locking Mechanism to ensure the Master Side Aid in place.
CAUTION:Make sure hands and fingers are free and clear of Locking Mechanism.


Step 4:
Bring the Master Plate Assembly to a position directly over the Tool Plate Assembly. The Master Plate Assembly's face should be parallel to the Tool Plate Assembly's face. Ensure that the orientation of the Master and Tool Assemblies are such that the Flat Alignment marks correspond.

| NOTES: UNLESS OTHERWISE SPECIFIED. |  |  | $\begin{aligned} & \text { 1031 Goodworth Drive, Apex, NC 27539, USA } \\ & \text { Tel: +1.919.772.0115 Email: info@ati-ia.com } \\ & \text { Fax: + +1.919.772.8259 www.ati-ia.com } \\ & \text { ISO 9001 Registered Company } \end{aligned}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| DO NOT SCALE DRAWING. ALL DIMENSIONS ARE IN MILLIMETERS. <br> 3rd ANGLE PROJECTION |  |  |  |  |  |
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|  | DRAWn BY: E. Donkor 1/7/2014 | ${ }^{\text {TTLE }}$ Q 1210 Ali |  |  |  |
|  | CHECKED BY: D. Norton 1/16/2014 | QC-1210 Alignment Teaching Aids |  |  |  |
|  |  | SCALE | SIIE | DRAWING NUMBER | REVISION |
|  | ProJect \# 140103-2 sheet 1 of 2 | 1:4 | B | 9230-20-7701 | 02 |


| Rev. | Description | Initiator | Date |
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| - | See Sheetl | - | - |



Step 5:
Move the Master Plate Assembly slowly downward unti the Master and Tool Side Aids are approximately 1 mm apart.

Step 6:
Adjust the position of the robot to correct for any lateral misalignment. Use the Alignment Marks to align the Tool Side and Master Side Aids.

Step 7
Record the robot coordinates from Step 6. A correction must now be made to the $Z$ coordinate to account for the thickness of the Tool and Master Side Teaching Aids. Only in this way can the correct "Pick-up and "Replacement" coordinates be determine erform the following cal acement" location:

Z "Pick-up" Coordinate = (Z Coordinate from Step 6) - (70mm)

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DRAWn BY: E. Donkor 1/7/2014
CHECKED bY: D. Norton 1/16/2014

