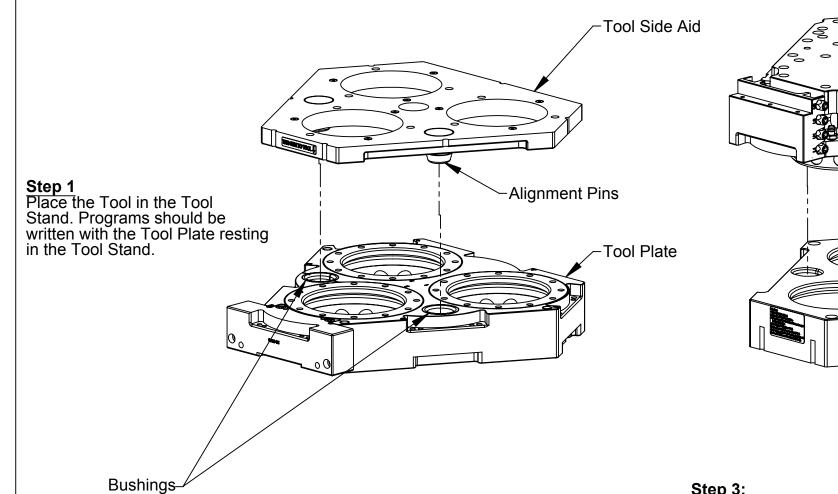
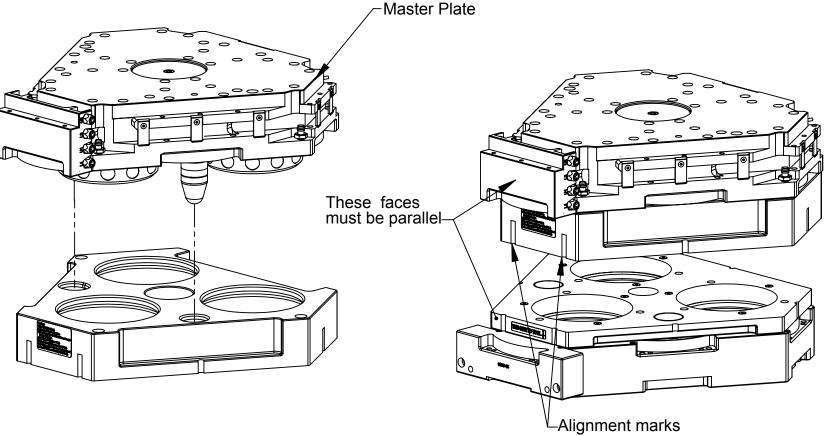
Rev.	Description	Initiator	Date
01	Initial Drawing	ERDO	1/7/2014
02	ECO 12273: Changed arrow formatting, updated 9005-20-2286.	DBoh	6/20/2014



Mount the Tool Side aid over the Tool Plate by inserting the Locating Pins

Step 2:

into the Bushings.

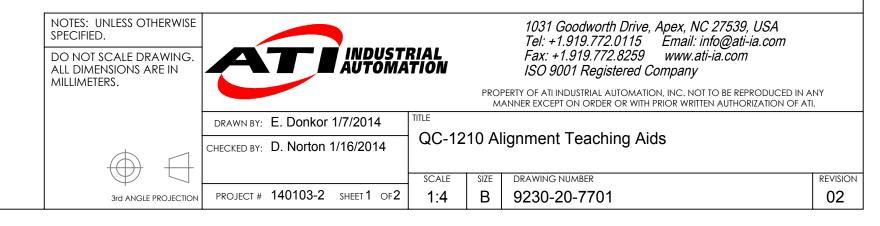


Mount the Master Side Aid to the QC Master Plate ensuring that the taper pins enter the corresponding holes in the Master Side Aid.

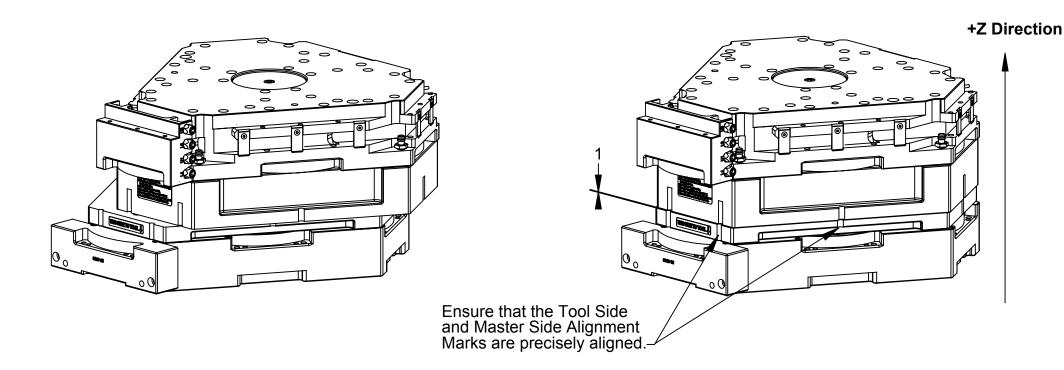
Energize the Locking Mechanism to ensure the Master Side Aid in place.

CAUTION: Make sure hands and fingers are free and clear of Locking Mechanism.

Step 4:
Bring the Master Plate Assembly to a position directly over the Tool Plate Assembly. The Master Plate Assembly's face should be parallel to the Tool Plate Assembly's face. Ensure that the orientation of the Master and Tool Assemblies are such that the Flat Alignment marks correspond.



Rev.	Description	Initiator	Date
-	See Sheet1	-	-

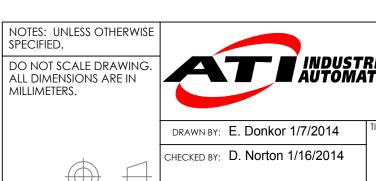


Step 5: Move the Master Plate Assembly slowly downward until the Master and Tool Side Aids are approximately 1mm apart.

Step 6: Adjust the position of the robot to correct for any lateral misalignment. Use the Alignment Marks to align the Tool Side and Master Side Aids.

Step 7
Record the robot coordinates from Step 6. A correction must now be made to the Z coordinate to account for the thickness of the Tool and Master Side Teaching Aids. Only in this way can the correct "Pick-up" and "Replacement" coordinates be determined. Perform the following calculation to determine the "Pick-up" and "Replacement" location:

Z "Pick-up" Coordinate = (Z Coordinate from Step 6) - (70mm)



3rd ANGLE PROJECTION

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REVISION

02

QC-1210 Alignment Teaching Aids

DRAWING NUMBER SCALE PROJECT # 140103-2 SHEET 2 OF 2 1:3 В 9230-20-7701